Quadrotor Modeling And Control

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Multicopter Design and Control Practice - Quan Quan 2020-04-17
As the sister book to “Introduction to Multicopter Design and Control,” published by Springer in 2017, this book focuses on using a practical process to help readers to deepen their understanding of multicopter design and control. Novel tools with tutorials on multicopters are presented, which can help readers move from theory to practice. Experiments presented in this book employ: (1) The most widely-used flight platform – multicopters – as a flight platform; (2) The most widely-used flight pilot hardware – Pixhawk – as a control platform; and (3) One of the most widely-used programming languages in the field of control engi-neering – MATLAB + Simulink – as a programming language. Based on the current advanced development concept Model-Based Design (MBD)process, the three aspects mentioned above are closely linked. Each experiment is implemented in MATLAB and Simulink, and the numerical simula-tion test is carried out on a built simulation platform. Readers can upload the controller to the Pixhawk autopilot using automatic code generation technology and form a closed loop with a given real-time simulator for Hardware-In-the-Loop (HIL) testing. After that, the actual flight with the Pixhawk autopilot can be performed. This is by far the most complete and clear guide to modern drone fundamentals I’ve seen.It covers every element of these advanced aerial robots and walks through examples and tutorials based on the industry’s leading open-source software and tools. Read this book, and you’ll be well prepared to work at the leading edge of this exciting new industry. Chris Anderson, CEO 3DR and Chairman, the Linux Foundation’s Dronecode Project The development of a multicopter and its applications is very challenging in the robotics area due to the multidomain knowledge involved. This book systematically addresses the design, simulation and implementation of multicopters with the industrial leading workflow – Model-Based Design, commonly used in the automotive and aero-defense industries. With this book, researchers and engineers can seamlessly apply the concepts, workflows, and tools in other engineering areas, especially robot design and robotics ap-plication development. Dr. Yanliang Zhang, Founder of Weston Robot, EX-product Manager of Robotics System Toolbox at the MathWorks
Advanced Robust Nonlinear Control Approaches for Quadrotor Unmanned Aerial Vehicle - Moussa Labbadi 2021-10-21
This book studies selected advanced flight control schemes for an uncertain quadrotor unmanned aerial vehicle (UAV) systems in the presence of constant external disturbances, parametric uncertainties, measurement noise, time-varying external disturbances, and random external disturbances. Furthermore, in all the control techniques proposed in this book, it includes the simulation results with comparison to other nonlinear control schemes recently developed for the tracking control of a quadrotor UAV. The main contributions of the present book for quadrotor UAV systems are as follows: (i) the proposed control methods are based on the high-order sliding mode controller (SMC) and hybrid control algorithm with an optimization method. (ii) the finite-time control schemes are developed by using fast terminal SMC (FTSMC), nonsingular FTSMC (NFTSMC), global time-varying SMC, and adaptive laws. (iii) the fractional-order flight control schemes are developed by using the fractional-order calculus theory, super twisting algorithm, NFTSMC, and the SMC. This book covers the research history and importance of quadrotor system subject to system uncertainties, external wind disturbances, and noise measurements, as well as the research status of advanced flight control methods, adaptive flight control methods, and flight control based on fractional-order theory. The book would be interesting to most academic undergraduate, postgraduates, researchers on flight control for drones and applications of advanced controllers in engineering field. This book presents a must-survey for advanced finite-time control for quadrotor system. Some parts of this book have the potential of becoming the courses for the modelling and control of autonomous flying machines. Readers (academic researcher, undergraduate student, postgraduate student, MBA/executive, and education practitioner) interested in nonlinear control methods find this book an investigation. This book can be used as a good reference for the academic research on the control theory, drones, terminal sliding mode control, and related to this or used in Ph.D. study of control theory and their application in field engineering.
Experimental Robotics - Oussama Khatib 2013-08-20
Incorporating papers from the 12th International Symposium on Experimental Robotics (ISER), December 2010, this book examines the latest advances across the various fields of robotics. Offers insights on both theoretical concepts and experimental results.
Unmanned Aerial Vehicles - Information Resources Management Association 2019
First used in military applications, unmanned aerial vehicles are becoming an integral aspect of modern society and are expanding into the commercial, scientific, recreational, agricultural, and surveillance sectors. With the increasing use of these drones by government officials, business professionals, and civilians, more research is needed to understand their complexity both in design and function. Unmanned Aerial Vehicles: Breakthroughs in Research and Practice is a critical source of academic knowledge on the design, construction, and maintenance of drones, as well as their applications a.
2019 19th International Conference on Advanced Robotics (ICAR) - IEEE Staff 2019-12-02
The 19th International Conference on Advanced Robotics (ICAR), one of the oldest and most prestigious robotics conference in the world, will be held in Brazil, hosted by the Federal University of Minas Gerais ICAR 2019 will offer you an unparalleled experience with excellent technical programs and social activities Contributed Papers Papers reporting original research in the general areas of Robotics, Automation, Artificial Intelligence, Computer Vision, Machine Learning, and applications are welcome Six pages in standard ICAR format are allowed for each paper, including figures A maximum of two additional pages is permitted Prospective authors should submit PDF versions of their papers We also invite authors to submit a video clip to complement the submission Detailed instructions for submission are available on the conference website
Nonlinear Dynamical Control Systems - Henk Nijmeijer 2013-03-14
This volume deals with controllability and observability properties of nonlinear systems, as well as various ways to obtain input-output representations. The emphasis is on fundamental notions as (controlled) invariant distributions and submanifolds, together with algorithms to compute the required feedbacks.
Design, Modeling and Control of Aerial Robots for Physical Interaction and Manipulation - Burak Yüksel 2017-06-10
Aerial robots, meaning robots with flying capabilities, are essentially robotic platforms, which are autonomously controlled via some sophisticated control engineering tools. Similar to aerial vehichles, they can overcome the gravitational forces thanks to their design and/or actuation type. What makes them different from the conventional aerial vehicles, is the level of their autonomy. Reducing the complexity for piloting of such robots/vehicles provide the human operator more freedom and comfort. With their increasing autonomy, they can perform many complicated tasks by their own (such as surveillance, monitoring, or inspection), leaving the human operator the most high-level decisions to be made, if necessary. In this way they can be operated in hazardous and challenging environments, which might posses high risks to the human health. Thanks to their wide range of usage, the ongoing researches on aerial robots is expected to have an increasing impact on the human life. Aerial Physical Interaction (APhI) is a case, in which the aerial robot exerts meaningful forces and torques (wrench) to its

environment while preserving its stable flight. In this case, the robot does not try avoiding every obstacle in its environment, but prepare itself for embracing the effect of a physical interaction, furthermore turn this interaction into some meaningful robotic tasks. Aerial manipulation can be considered as a subset of APhI, where the flying robot is designed and controlled in purpose of manipulating its environment. A clear motivation of using aerial robots for physical interaction, is to benefit their great workspace and agility. Moreover, developing robots that can perform not only APhI but also aerial manipulation can bring the great workspace of the flying robots together with the vast dexterity of the manipulating arms. This thesis work is addressing the design, modeling and control problem of these aerial robots for the purpose of physical interaction and manipulation. Using the nonlinear mathematical models of the robots at hand, in this thesis several different control methods (IDA-PBC, Exact Linearization, Differential Flatness Based Control) for APhI and aerial manipulation tasks have been developed and proposed. Furthermore, novel design tools (e.g. new rigid/elastic manipulating arms, hardware, software) to be used together with miniature aerial robots are presented within this thesis, which contributes to the robotics society not only in terms of concrete theory but also practical implementation and experimental robotics.

Modelling and Control of Mini-Flying Machines - Pedro Castillo Garcia 2006-03-30

Modelling and Control of Mini-Flying Machines is an exposition of models developed to assist in the motion control of various types of mini-aircraft: • Planar Vertical Take-off and Landing aircraft; • helicopters; • quadrotor mini-rotorcraft; • other fixed-wing aircraft; • blimps. For each of these it propounds: • detailed models derived from Euler-Lagrange methods; • appropriate nonlinear control strategies and convergence properties; • real-time experimental comparisons of the performance of control algorithms; • review of the principal sensors, on-board electronics, real-time architecture and communications systems for mini-flying machine control, including discussion of their performance; • detailed explanation of the use of the Kalman filter to flying machine localization. To researchers and students in nonlinear control and its applications Modelling and Control of Mini-Flying Machines provides valuable insights to the application of real-time nonlinear techniques in an always challenging area.

Introduction to Multicopter Design and Control - Quan Quan 2017-06-23

This book is the first textbook specially on multicopter systems in the world. It provides a comprehensive overview of multicopter systems, rather than focusing on a single method or technique. The fifteen chapters are divided into five parts, covering the topics of multicopter design, modeling, state estimation, control, and decision-making. It differs from other books in the field in three major respects: it is basic and practical, offering self-contained content and presenting hands-on methods; it is comprehensive and systematic; and it is timely. It is also closely related to the autopilot that users often employ today and provides insights into the code employed. As such, it offers a valuable resource for anyone interested in multicopters, including students, teachers, researchers, and engineers. This introductory text is a welcome addition to the literature on multicopter design and control, on which the author is an acknowledged authority. The book is directed to advanced undergraduate and beginning graduate students in aeronautical and control (or electrical) engineering, as well as to multicopter designers and hobbyists. ------- Professor W. Murray Wonham, University of Toronto "This is the single best introduction to multicopter control. Clear, comprehensive and progressing from basic principles to advanced techniques, it's a must read for anyone hoping to learn how to design flying robots." ------- Chris Anderson, 3D Robotics CEO.

Applied Nonlinear Control - Jean-Jacques E. Slotine 1991

In this work, the authors present a global perspective on the methods available for analysis and design of non-linear control systems and detail specific applications. They provide a tutorial exposition of the major non-linear systems analysis techniques followed by a discussion of available non-linear design methods.

Modeling and Control Simulation for Autonomous Quadrotor - Idris Eko Putro 2011-03

The use of Quadrotor UAVs has been widely well known. It has capability to hover, vertical take-off and landing (VTOL) with having less complexity in vehicle dynamics compared with small helicopter. It is basically an unstable system and exhibits nonlinear behavior. This book describes the development of nonlinear model of quadrotor dynamics derived from Newton-Euler formulation and presented under Matlab/Simulink environment. The Model is equipped by Stability Augmentation System (SAS) to maintain the quadrotor level flight (attitude stability). The autonomous mission for this vehicle is fixed for trajectory following. LQR Optimal control was chosen to accomplish this mission.

Modern Robotics - Kevin M. Lynch 2017-05-25

This introduction to robotics offers a distinct and unified perspective of the mechanics, planning and control of robots. Ideal for self-learning, or for courses, as it assumes only freshman-level physics, ordinary differential equations, linear algebra and a little bit of computing background. Modern Robotics presents the state-of-the-art, screw-theoretic techniques capturing the most salient physical features of a robot in an intuitive geometrical way. With numerous exercises at the end of each chapter, accompanying software written to reinforce the concepts in the book and video lectures aimed at changing the classroom experience, this is the go-to textbook for learning about this fascinating subject.

2016 International Conference on Electrical, Electronics, and Optimization Techniques (ICEEOT) - IEEE Staff 2016-03-03

The aim of the conference is to bring Students, Engineers, Researchers and Scientists to single platform for share their knowledge and ideas in the recent trends in the field of Engineering, Science and Technology

Model Free Adaptive Control - Zhongsheng Hou 2013-09-24

Model Free Adaptive Control: Theory and Applications summarizes theory and applications of model-free adaptive control (MFAC). MFAC is a novel adaptive control method for the unknown discrete-time nonlinear systems with time-varying parameters and time-varying structure, and the design and analysis of MFAC merely depend on the measured input and output data of the controlled plant, which makes it more applicable for many practical plants. This book covers new concepts, including pseudo partial derivative, pseudo gradient, pseudo Jacobian matrix, and generalized Lipschitz conditions, etc.; dynamic linearization approaches for nonlinear systems, such as compact-form dynamic linearization, partial-form dynamic linearization, and full-form dynamic linearization; a series of control system design methods, including MFAC prototype, model-free adaptive predictive control, model-free adaptive iterative learning control, and the corresponding stability analysis and typical applications in practice. In addition, some other important issues related to MFAC are also discussed. They are the MFAC for complex connected systems, the modularized controller designs between MFAC and other control methods, the robustness of MFAC, and the symmetric similarity for adaptive control system design. The book is written for researchers who are interested in control theory and control engineering, senior undergraduates and graduated students in engineering and applied sciences, as well as professional engineers in process control.

Unmanned Aerial Vehicles: Breakthroughs in Research and Practice - Management Association, Information Resources 2019-05-03

First used in military applications, unmanned aerial vehicles are becoming an integral aspect of modern society and are expanding into the commercial, scientific, recreational, agricultural, and surveillance sectors. With the increasing use of these drones by government officials, business professionals, and civilians, more research is needed to understand their complexity both in design and function. Unmanned Aerial Vehicles: Breakthroughs in Research and Practice is a critical source of academic knowledge on the design, construction, and maintenance of drones, as well as their applications across all aspects of society. Highlighting a range of pertinent topics such as intelligent systems, artificial intelligence, and situation awareness, this publication is an ideal reference source for military consultants, military personnel, business professionals, operation managers, surveillance companies, agriculturalists, policymakers, government officials, law enforcement, IT professionals, academicians, researchers, and graduate-level students.

Vibration Engineering and Technology of Machinery - José Manoel Balthazar 2021-03-03

This volume gathers the latest advances, innovations and applications in the field of vibration and technology of machinery, as presented by leading international researchers and engineers at the XV International Conference on Vibration Engineering and Technology of Machinery (VETOMAC), held in Curitiba, Brazil on November 10-15, 2019. Topics include concepts and methods in dynamics, dynamics of mechanical and structural systems, dynamics and control, condition monitoring, machinery and structural dynamics, rotor dynamics, experimental techniques, finite element model updating, industrial case studies, vibration control and energy harvesting, and MEMS. The contributions, which were selected through a rigorous international peer-review process, share exciting ideas that will spur novel research directions and

foster new multidisciplinary collaborations.

Robotics, Vision and Control - Peter Corke 2011-09-05

The author has maintained two open-source MATLAB Toolboxes for more than 10 years: one for robotics and one for vision. The key strength of the Toolboxes provide a set of tools that allow the user to work with real problems, not trivial examples. For the student the book makes the algorithms accessible, the Toolbox code can be read to gain understanding, and the examples illustrate how it can be used —instant gratification in just a couple of lines of MATLAB code. The code can also be the starting point for new work, for researchers or students, by writing programs based on Toolbox functions, or modifying the Toolbox code itself. The purpose of this book is to expand on the tutorial material provided with the toolboxes, add many more examples, and to weave this into a narrative that covers robotics and computer vision separately and together. The author shows how complex problems can be decomposed and solved using just a few simple lines of code, and hopefully to inspire up and coming researchers. The topics covered are guided by the real problems observed over many years as a practitioner of both robotics and computer vision. It is written in a light but informative style, it is easy to read and absorb, and includes a lot of Matlab examples and figures. The book is a real walk through the fundamentals of robot kinematics, dynamics and joint level control, then camera models, image processing, feature extraction and epipolar geometry, and bring it all together in a visual servo system. Additional material is provided at http://www.petercorke.com/RVC

Intelligent Human Computer Interaction - Uma Shanker Tiwary 2020-04-11

This volume constitutes the proceedings of the 11th International Conference on Intelligent Human Computer Interaction, IHCI 2019, held in Allahabad, India, in December 2019. The 25 full papers presented in this volume were carefully reviewed and selected from 73 submissions. The papers are grouped in the following topics: EEG and other biological signal based interactions; natural language, speech and dialogue processing; vision based interactions; assistive living and rehabilitation; and applications of HCI.

Aerial Robotic Workers - George Nikolakopoulos 2022-11-10

Aerial Robotic Workers: Design, Modeling, Control, Vision and Their Applications provides an in-depth look at both theory and practical applications surrounding the Aerial Robotic Worker (ARW). Emerging ARWs are fully autonomous flying robots that can assist human operations through their agile performance of aerial inspections and interaction with the surrounding infrastructure. This book addresses all the fundamental components of ARWs, starting with the hardware and software components and then addressing aspects of modeling, control, perception of the environment, and the concept of aerial manipulators, cooperative ARWs, and direct applications. The book includes sample codes and ROS-based tutorials, enabling the direct application of the chapters and real-life examples with platforms already existing in the market. Addresses the fundamental problems of UAVs with the ability of utilizing aerial tools in the fields of modeling, control, navigation, cooperation, vision and interaction with the environment Includes open source codes and libraries, providing a complete set of information for readers to start their experimentation with UAVs, and more specifically, ARWs Provides multiple, real-life examples and codes in MATLAB and ROS

Advanced Sliding Mode Control for Mechanical Systems - Jinkun Liu 2012-09-07

"Advanced Sliding Mode Control for Mechanical Systems: Design, Analysis and MATLAB Simulation" takes readers through the basic concepts, covering the most recent research in sliding mode control. The book is written from the perspective of practical engineering and examines numerous classical sliding mode controllers, including continuous time sliding mode control, discrete time sliding mode control, fuzzy sliding mode control, neural sliding mode control, backstepping sliding mode control, dynamic sliding mode control, sliding mode control based on observer, terminal sliding mode control, sliding mode control for robot manipulators, and sliding mode control for aircraft. This book is intended for engineers and researchers working in the field of control. Dr. Jinkun Liu works at Beijing University of Aeronautics and Astronautics and Dr. Xinhua Wang works at the National University of Singapore.

Handbook of Research on Advancements in Robotics and Mechatronics - Habib, Maki K. 2014-12-31

The field of mechatronics integrates modern engineering science and technologies with new ways of thinking, enhancing the design of products and manufacturing processes. This synergy enables the creation and evolution of new intelligent human-oriented machines. The Handbook of Research on Advancements in Robotics and Mechatronics presents new findings, practices, technological innovations, and theoretical perspectives on the the latest advancements in the field of mechanical engineering. This book is of great use to engineers and scientists, students, researchers, and practitioners looking to develop autonomous and smart products and systems for meeting today's challenges.

Autonomous Flying Robots - Kenzo Nonami 2010-09-15

The advance in robotics has boosted the application of autonomous vehicles to perform tedious and risky tasks or to be cost-effective substitutes for their - man counterparts. Based on their working environment, a rough classi cation of the autonomous vehicles would include unmanned aerial vehicles (UAVs), - manned ground vehicles (UGVs), autonomous underwater vehicles (AUVs), and autonomous surface vehicles (ASVs). UAVs, UGVs, AUVs, and ASVs are called UVs (unmanned vehicles) nowadays. In recent decades, the development of - manned autonomous vehicles have been of great interest, and different kinds of autonomous vehicles have been studied and developed all over the world. In part- ular, UAVs have many applications in emergency situations; humans often cannot come close to a dangerous natural disaster such as an earthquake, a ood, an active volcano, or a nuclear disaster. Since the development of the rst UAVs, research efforts have been focused on military applications. Recently, however, demand has arisen for UAVs such as aero-robotsand ying robotsthat can be used in emergency situations and in industrial applications. Among the wide variety of UAVs that have been developed, small-scale HUAVs (helicopter-based UAVs) have the ability to take off and land vertically as well as the ability to cruise in ight, but their most importantcapability is hovering. Hoveringat a point enables us to make more eff- tive observations of a target. Furthermore, small-scale HUAVs offer the advantages of low cost and easy operation.

Simulation, Modeling, and Programming for Autonomous Robots - Itsuki Noda 2012-10-20

This book constitutes the refereed proceedings of the Third International Conference on Simulation, Modeling, and Programming for Autonomous Robots, SIMPAR 2012, held in Tsukuba, Japan, in November 2012. The 33 revised full papers and presented together with 3 invited talks were carefully reviewed and selected from 46 submissions. Ten papers describe design of complex behaviors of autonomous robots, 9 address software layers, 8 papers refer to related modeling and learning. The papers are organized in topical sections on mobile robots, software modeling and architecture and humanoid and biped robots.

Smart Sensors Measurements and Instrumentation - Santhosh K V 2021-05-10

This book presents the select proceedings of Control Instrumentation and System Conference, (CISCON 2020) held at Manipal Institute of Technology, MAHE, Manipal. It examines a wide spectrum covering the latest trends in the fields of instrumentation, sensors and systems, and industrial automation and control. The topics covered include image and signal processing, robotics, renewable energy, power systems and power drives, performance attributes of MEMS, multi-sensor data fusion, machine learning, optimization techniques, process control, safety monitoring, safety critical control, supervisory control, system modeling and virtual instrumentation. The book is a valuable reference for researchers and professionals interested in sensors, adaptive control, automation and control and allied fields.

Aircraft Control and Simulation - Brian L. Stevens 2015-10-02

Get a complete understanding of aircraft control and simulation Aircraft Control and Simulation: Dynamics, Controls Design, and Autonomous Systems, Third Edition is a comprehensive guide to aircraft control and simulation. This updated text covers flight control systems, flight dynamics, aircraft modeling, and flight simulation from both classical design and modern perspectives, as well as two new chapters on the modeling, simulation, and adaptive control of unmanned aerial vehicles. With detailed examples, including relevant MATLAB calculations and FORTRAN codes, this approachable yet detailed reference also provides access to supplementary materials, including chapter problems and an instructor's solution manual. Aircraft control, as a subject area, combines an understanding of aerodynamics with knowledge of the physical systems of an aircraft. The ability to analyze the performance of an aircraft both in the real world and in computer-simulated flight is essential to maintaining proper control and function of the aircraft. Keeping up with the skills necessary to perform this analysis is critical

for you to thrive in the aircraft control field. Explore a steadily progressing list of topics, including equations of motion and aerodynamics, classical controls, and more advanced control methods Consider detailed control design examples using computer numerical tools and simulation examples Understand control design methods as they are applied to aircraft nonlinear math models Access updated content about unmanned aircraft (UAVs) Aircraft Control and Simulation: Dynamics, Controls Design, and Autonomous Systems, Third Edition is an essential reference for engineers and designers involved in the development of aircraft and aerospace systems and computer-based flight simulations, as well as upper-level undergraduate and graduate students studying mechanical and aerospace engineering.

Modeling and Neural Control of Quadrotor Helicopter - Yasir Amir Khan Niazi 2010-08

Quadrotor is a rotorcraft with four vertically oriented propellers. Two of the propellers spin in clockwise direction and the other two in the counter clockwise direction. For a Quadrotor Helicopter a stabilizing controller is always needed. In this book Artificial Neural Networks based Control Methodology to stabilize the a Quadrotor Helicopoter, has been explained. Firstly a mathematical model of Quadrotor is developed. A simplified approach is adopted using momentum theory, where the gyroscopic effect and air friction on machine s body has been neglected, resulting in a simplified model which is useful in designing a controller to stabilize the machine in hover state. The proposed model is nonlinear since the rotor dynamics are function of square of motor inputs. In the controller designing, Direct Inverse Neural Network Control methodology is employed. For that matter 16,8,4-MLP, 16,16,4-MLP and 16,64,4-MLP are used to control the Quadrotor plant. There performance is compared using simulation results. Direct Inverse Control using 16,64,4-MLP gives the best performance amongst all the other considered.

Advanced Robust Nonlinear Control Approaches for Quadrotor Unmanned Aerial Vehicle - Moussa Labbadi 2021-09-14

This book studies selected advanced flight control schemes for an uncertain quadrotor unmanned aerial vehicle (UAV) systems in the presence of constant external disturbances, parametric uncertainties, measurement noise, time-varying external disturbances, and random external disturbances. Furthermore, in all the control techniques proposed in this book, it includes the simulation results with comparison to other nonlinear control schemes recently developed for the tracking control of a quadrotor UAV. The main contributions of the present book for quadrotor UAV systems are as follows: (i) the proposed control methods are based on the high-order sliding mode controller (SMC) and hybrid control algorithm with an optimization method. (ii) the finite-time control schemes are developed by using fast terminal SMC (FTSMC), nonsingular FTSMC (NFTSMC), global time-varying SMC, and adaptive laws. (iii) the fractional-order flight control schemes are developed by using the fractional-order calculus theory, super twisting algorithm, NFTSMC, and the SMC. This book covers the research history and importance of quadrotor system subject to system uncertainties, external wind disturbances, and noise measurements, as well as the research status of advanced flight control methods, adaptive flight control methods, and flight control based on fractional-order theory. The book would be interesting to most academic undergraduate, postgraduates, researchers on flight control for drones and applications of advanced controllers in engineering field. This book presents a must-survey for advanced finite-time control for quadrotor system. Some parts of this book have the potential of becoming the courses for the modelling and control of autonomous flying machines. Readers (academic researcher, undergraduate student, postgraduate student, MBA/executive, and education practitioner) interested in nonlinear control methods find this book an investigation. This book can be used as a good reference for the academic research on the control theory, drones, terminal sliding mode control, and related to this or used in Ph.D. study of control theory and their application in field engineering.

Control PID avanzado - Karl Johan Åström 2009

Modeling, Design and Simulation of Systems - Mohamed Sultan Mohamed Ali 2017-08-24

This two-volume set CCIS 751 and CCIS 752 constitutes the proceedings of the 17th Asia Simulation Conference, AsiaSim 2017, held in Malacca, Malaysia, in August/September 2017. The 124 revised full papers presented in this two-volume set were carefully reviewed and selected from 267 submissions. The papers contained in these proceedings address challenging issues in modeling and simulation in various fields such as embedded systems; symbiotic simulation; agent-based simulation; parallel and distributed simulation; high performance computing; biomedical engineering; big data; energy, society and economics; medical processes; simulation language and software; visualization; virtual reality; modeling and Simulation for IoT; machine learning; as well as the fundamentals and applications of computing.

9th International Conference on Robotic, Vision, Signal Processing and Power Applications - Haidi Ibrahim 2016-09-29

The proceeding is a collection of research papers presented, at the 9th International Conference on Robotics, Vision, Signal Processing & Power Applications (ROVISP 2016), by researchers, scientists, engineers, academicians as well as industrial professionals from all around the globe to present their research results and development activities for oral or poster presentations. The topics of interest are as follows but are not limited to: • Robotics, Control, Mechatronics and Automation • Vision, Image, and Signal Processing • Artificial Intelligence and Computer Applications • Electronic Design and Applications • Telecommunication Systems and Applications • Power System and Industrial Applications • Engineering Education

Nonlinear Control Systems - Alberto Isidori 2013-04-17

The purpose of this book is to present a self-contained description of the fun damentals of the theory of nonlinear control systems, with special emphasis on the differential geometric approach. The book is intended as a graduate text as weil as a reference to scientists and engineers involved in the analysis and design of feedback systems. The first version of this book was written in 1983, while I was teach ing at the Department of Systems Science and Mathematics at Washington University in St. Louis. This new edition integrates my subsequent teaching experience gained at the University of Illinois in Urbana-Champaign in 1987, at the Carl-Cranz Gesellschaft in Oberpfaffenhofen in 1987, at the University of California in Berkeley in 1988. In addition to a major rearrangement of the last two Chapters of the first version, this new edition incorporates two additional Chapters at a more elementary level and an exposition of some relevant research findings which have occurred since 1985.

Proceedings of the 2nd International Conference on Electronic Engineering and Renewable Energy Systems - Bekkay Hajji 2020-08-14

This book includes papers presented at the Second International Conference on Electronic Engineering and Renewable Energy (ICEERE 2020), which focus on the application of artificial intelligence techniques, emerging technology and the Internet of things in electrical and renewable energy systems, including hybrid systems, micro-grids, networking, smart health applications, smart grid, mechatronics and electric vehicles. It particularly focuses on new renewable energy technologies for agricultural and rural areas to promote the development of the Euro-Mediterranean region. Given its scope, the book is of interest to graduate students, researchers and practicing engineers working in the fields of electronic engineering and renewable energy.

WITS 2020 - Saad Bennani 2021-07-21

This book presents peer-reviewed articles from the 6th International Conference on Wireless Technologies, Embedded and Intelligent Systems (WITS 2020), held at Fez, Morocco. It presents original research results, new ideas and practical lessons learnt that touch on all aspects of wireless technologies, embedded and intelligent systems. WITS is an international conference that serves researchers, scholars, professionals, students and academicians looking to foster both working relationships and gain access to the latest research results. Topics covered include Telecoms & Wireless Networking Electronics & Multimedia Embedded & Intelligent Systems Renewable Energies.

Flight Formation Control - Josep Guerrero 2012-12-17

In the last decade the development and control of UnmannedAerial Vehicles (UAVs) has attracted a lot of interest. Bothresearchers and companies have a growing interest in improving thistype of vehicle given their many civilian and militaryapplications. This book presents the state of the art in the area of UAV FlightFormation. The coordination and robust consensus approaches arepresented in detail as well as formation flight control strategieswhich are validated in experimental platforms. It aims at helpingstudents and academics alike to better understand what coordinationand flight formation control can make possible. Several novel methods are presented: - controllability and observability of multi-agent systems; - robust consensus; - flight formation control; - stability of formations over noisy networks; which generate solutions of guaranteed performance for UAV FlightFormation. Contents 1. Introduction, J.A. Guerrero. 2. Theoretical Preliminaries, J.A. Guerrero. 3. Multiagent Coordination Strategies, J.A. Guerrero, R. Lozano,M.W. Spong, N. Chopra. 4. Robust Control Design for Multiagent Systems with

ParametricUncertainty, J.A. Guerrero, G. Romero. 5. On Adaptive and Robust Controlled Synchronization of NetworkedRobotic Systems on Strongly Connected Graphs, Y.-C. Liu, N.Chopra. 6. Modeling and Control of Mini UAV, G. Flores Colunga, J.A.Guerrero, J. Escareño, R. Lozano. 7. Flight Formation Control Strategies for Mini UAVs, J.A.Guerrero. 8. Formation Based on Potential Functions, L. García, A.Dzul. 9. Quadrotor Vision-Based Control, J.E. Gomez-Balderas, J.A.Guerrero, S. SALAZAR, R. Lozano, P. Castillo. 10. Toward Vision-Based Coordination of Quadrotor Platoons, L.R.García Carrillo, J.A. Guerrero, R. Lozano. 11. Optimal Guidance for Rotorcraft Platoon Formation Flying inWind Fields, J.A. Guerrero, Y. Bestaoui, R. Lozano. 12. Impact of Wireless Medium Access Protocol on the QuadrotorFormation Control, J.A. Guerrero, Y. Challal, P. Castillo. 13. MAC Protocol for Wireless Communications, A. Mendez, M.Panduro, O. Elizarraras, D. Covarrubias. 14. Optimization of a Scannable Pattern for Bidimensional AntennaArrays to Provide Maximum Performance, A. Reyna, M.A. Panduro, A.Mendez.

New Trends in Robot Control - Jawhar Ghommam 2020-02-13

This book presents solutions to control problems in a number of robotic systems and provides a wealth of worked-out examples with full analytical and numerical details, graphically illustrated to aid in reader comprehension. It also presents relevant studies on and applications of robotic system control approaches, as well as the latest findings from interdisciplinary theoretical studies. Featuring chapters on advanced control (fuzzy, neural, backstepping, sliding mode, adaptive, predictive, diagnosis, and fault-tolerant control), the book will equip readers to easily tailor the techniques to their own applications. Accordingly, it offers a valuable resource for researchers, engineers, and students in the field of robotic systems.

Small Unmanned Aircraft - Randal W. Beard 2012-02-26

Autonomous unmanned air vehicles (UAVs) are critical to current and future military, civil, and commercial operations. Despite their importance, no previous textbook has accessibly introduced UAVs to students in the engineering, computer, and science disciplines--until now. Small Unmanned Aircraft provides a concise but comprehensive description of the key concepts and technologies underlying the dynamics, control, and guidance of fixed-wing unmanned aircraft, and enables all students with an introductory-level background in controls or robotics to enter this exciting and important area. The authors explore the essential underlying physics and sensors of UAV problems, including low-level autopilot for stability and higher-level autopilot functions of path planning. The textbook leads the student from rigid-body dynamics through aerodynamics, stability augmentation, and state estimation using onboard sensors, to maneuvering through obstacles. To facilitate understanding, the authors have replaced traditional homework assignments with a simulation project using the MATLAB/Simulink environment. Students begin by modeling rigid-body dynamics, then add aerodynamics and sensor models. They develop low-level autopilot code, extended Kalman filters for state estimation, path-following routines, and high-level path-planning algorithms. The final chapter of the book focuses on UAV guidance using machine vision. Designed for advanced undergraduate or graduate students in engineering or the sciences, this book offers a bridge to the aerodynamics and control of UAV flight.

Advanced UAV Aerodynamics, Flight Stability and Control - Pascual Marqués 2017-04-27

Comprehensively covers emerging aerospace technologies Advanced UAV aerodynamics, flight stability and control: Novel concepts, theory and applications presents emerging aerospace technologies in the rapidly growing field of unmanned aircraft engineering. Leading scientists, researchers and inventors describe the findings and innovations accomplished in current research programs and industry applications throughout the world. Topics included cover a wide range of new aerodynamics concepts and their applications for real world fixed-wing (airplanes), rotary wing (helicopter) and quad-rotor aircraft. The book begins with two introductory chapters that address fundamental principles of aerodynamics and flight stability and form a knowledge base for the student of Aerospace Engineering. The book then covers aerodynamics of fixed wing, rotary wing and hybrid unmanned aircraft, before introducing aspects of aircraft flight stability and control. Key features: Sound technical level and inclusion of high-quality experimental and numerical data. Direct application of the aerodynamic technologies and flight stability and control principles described in the book in the development of real-world novel unmanned aircraft concepts. Written by world-class academics, engineers, researchers and inventors from prestigious institutions and industry. The book provides up-to-date information in the field of Aerospace Engineering for university students and lecturers, aerodynamics researchers, aerospace engineers, aircraft designers and manufacturers.

Advances in Unmanned Aerial Vehicles - Kimon P. Valavanis 2008-02-26

The past decade has seen tremendous interest in the production and refinement of unmanned aerial vehicles, both fixed-wing, such as airplanes and rotary-wing, such as helicopters and vertical takeoff and landing vehicles. This book provides a diversified survey of research and development on small and miniature unmanned aerial vehicles of both fixed and rotary wing designs. From historical background to proposed new applications, this is the most comprehensive reference yet.

L1 Adaptive Control Theory - Naira Hovakimyan 2010-09-30

Contains results not yet published in technical journals and conference proceedings.

Nonlinear Model Predictive Control - Lalo Magni 2009-05-25

Over the past few years significant progress has been achieved in the field of nonlinear model predictive control (NMPC), also referred to as receding horizon control or moving horizon control. More than 250 papers have been published in 2006 in ISI Journals. With this book we want to bring together the contributions of a diverse group of internationally well recognized researchers and industrial practitioners, to critically assess the current status of the NMPC field and to discuss future directions and needs. The book consists of selected papers presented at the International Workshop on Assessment an Future Directions of Nonlinear Model Predictive Control that took place from September 5 to 9, 2008, in Pavia, Italy.